



MiCAT Planner Features

MiCAT Planner is Mitutoyo's latest software development for fast and efficient CMM part programming. Mitutoyo MiCAT Planner was developed to make the generation of measurement programs easier and faster. MiCAT Planner does this by fully automating generation of measurement programs based on CAD models containing PMI (primary GD&T) information, a DME configuration (Dimensional Measuring Equipment – e.g. CMM), and a pre-defined measurement strategy. The automatic generation can be controlled by defaults or with User defined rules. If no GD&T information is available, this can be added quickly and easily. The handling of MiCAT Planner is very easy and intuitive. Programs are made with just a few mouse clicks in just a few minutes instead of hours our days.

- 1. Import your Design Model (CAD Model)
- 2. Select your DME (CMM) configuration
- Utilizing the built in intelligence, User defined Rules, and User Parameter Settings, generate the CMM Measurement Program

Key features:

- DME (CMM) selection
- Automatic part placement
- Automatic selection of characteristic types for evaluation
- Feature-dependent measurement strategies
- GD&T Wizard for Design Models without PMI data

Program generation features:

- Design model import
 - Siemens PLM NX/Unigraphix
 - PTC ProE/Creo
 - Dassault Systems CATIA v5
 - ACIS (*.sat)
- Verification and editing of the automatically created measurement plan
- Characteristic based sensor selection chooses the best probe orientation
- Tool path minimized automatically for measuring sequence and probe changes
- Measurement program generation
- Translation of a measurement program to a GEOPAK part program

Benefits:

- Up to 90% time reduction for making CMM part programs, increased production & work flow
- Error free creation of part programs with easy checking and refinement, less rework & inspection cycle time
- Defined measurement strategies applied automatically, consistent measurement practices
- Design model support with or without PMI data, increased electronic data flexibility



.....





Design Model Support

- ProE: 16 Wildfire 5 | <u>Creo Parametric:</u> 1 to 2.0 w/PMI
- <u>UG:</u> 11 to 18 | <u>NX:</u> 1 to 8 w/PMI
- CATIA v5: R6 to 23 w/PMI
- ACIS

In order to generate a measurement program, the design model must have PMI (product manufacturing information). This can be defined in the original CAD file, or added manually in MiCAT Planner using the GD&T View.



DME (CMM) Gallery

The DME selection gallery enables you to load CMM configurations which have been created with MCOSMOS CMM SystemManager. CMM SystemManager in MCOSMOS is used to create CMM configurations, MiCAT Planner populates the DME gallery automatically with the list of configurations contained in the Configurations directory of MCOSMOS.

3D ACIS file (*.SAT)

All Supported Models (*.prt;*.prt.*;*.CATPart;*.SAT)

Since each CMM configuration has its own measuring range and probe system, MICAT Planner generates the measurement program using the selected configuration. As an example, if a CMM with a touch trigger probe is selected, then MiCAT Planner will only generate a measurement program using the sampling method of touch trigger measuring. If the CMM configuration selected includes a contact scanning probe, then MiCAT Planner allows the User to select either touch trigger or contact scanning to measure the part. The sampling method can be set globally or based on feature type.

MiCAT Planner Supported Equipment

CMM's	Probe Heads	Sensors		
BHN	PH9 & 9A	TP2, 20, & 6		
Bright-Strato	PH10M	TP200		
Crysta-Apex	10MQ	TP7		
KN	PH10T	SP25M		
LEGEX	PH6M	SP600 & 600Q		
MACH-V & 3A	PH6A	SP80		
STRATO-Apex	PH1	MPP100 & 300		

The columns in the above table are mutually exclusive of one another.







Program Generation Options

With MiCAT Planners Program Generation Options lets the user streamline the decision making for the settings to be used for each or all project plans for Generations Settings, Collision Avoidance Settings and CNC Parameters. The Program Generation Options settings with the Users input directly influences how the measurement program is created.

Generation Settings		
Tool selection		
Minimum percentage of feature area coverage	25	%
Maximum angle difference applied to cylinder, circle, cone and sphere	5.000000	
What happens if I change the tool selection setti	ngs?	
Evaluation order of characteristics		
Evaluation	At the end	•
What happens if I change the evaluation order o	As soon as possible	
	At the end	
Placement uncertainty		
х	50.000	mm
Y	50.000	mm
Z	50.000	mm (up)
Limit movement in Z to	DME table	•
What happens if I change the alignment uncerta	inty?	
	0-	-
Reduce runtime	On	
Reduce runtime automatically	Off	
Maximum percentage of feature area coverage reduction	5	%
What happens if I change the reduce runtime se	ttings?	

Collision Avoidance Settings – allows you to enable DME components and to specify various clearance distances.

- Enable DME components enable DME components to be included in collision avoidance clearance settings.
- Clearance distances for move types sets the clearance distance between DME and design model between measurements, to and from a measurement, or when measuring a point.
- Clearance distance between DME & other non-moving objects sets the clearance distance between DME and non-moving objects such as change racks or master balls.

CNC Parameters Speed settings Movement speed 519.60 mm/ 3.00 Measurement speed mm/ How can I change the CNC parameter for speed? Length settings and length. 0.500 Approach distance mm Retraction length 1.000 mm 100.000 Measurement length mm ow can I change the CNC parameter for length?

<u>Generation Settings</u> – enables you to change settings for Tool selection, Evaluation order of characteristics, Placement uncertainty & Reduce runtime.

- **Tool Selection** sets the minimum percentage of feature area coverage and the maximum angle difference between the selected tool and for cylinders, circles, cones and spheres.
- Evaluation Order of Characteristics changes the evaluation order of characteristics for the generated measurement program.
- Placement Uncertainty changes the allowable deviations between the physical alignment of the part and the placement of the design model in MiCAT Planner.
- **Reduce Runtime** –Turn On or Off the Reduce runtime automatically process. The Reduce runtime automatically process may reduce program execution time by changing feature order and by minimizing tool changes. The Reduce runtime group also enables you to set the maximum percentage of feature area coverage reduction.

Collision Avoidance Settings							
Enable DME components							
Master ball(s)	✓ Master ball(s)						
What happens if I enable or disable DME components?							
Clearance distances for mo	ve types						
Enter a collision avoidance cle	arance distance for each	h of these move-types					
Between measurements	5.000	mm V V					
To and from a measurement	5.000	mm					
When measuring a point	0.400	mm					
Clearance distance between DME and other non-moving objects							
To racks, master balls,	10.000	mm					
What happens if I change the	collision avoidance clea	rance distances?					

<u>CNC Parameters</u> – enables you to set the CNC parameters for speed and length.

- **Speed settings** controls the movement speed between the measurement approach points and the measurement speed at which the point(s) will be measured.
- Length settings sets the length for the Approach distance, Retraction length. and Measurement length.





Rules Editor

The Rules Editor is used to create, change and run rules that are applied to design model features and characteristics listed in the Plan View. Rules contain pre-defined parameter settings for measuring features or evaluating characteristics in the measurement program. The affected features or characteristics are defined in the Criteria pane, and the parameters for those features or characteristics are set in the Actions pane.

When a new project is created, all parameters have default settings. Rules are used to change the settings to userdesired values. Since a design model can contain a large amount of features and characteristics, setting the parameters individually for these items would be timeconsuming. The Rules Editor allows you to conveniently define the criteria and quickly apply actions to that criteria.

Default rules are provided for both default project templates, Touch Trigger Template and Contact Scanning Template.

es Ci	iteria			Add
I Feature Measurement	eature	• =	Circle	•
I Characteristics	Radius	• <=	• 9.999	
/linder Measurement (in touch trigger mode)	Material direction	• =	 Inner 	•
rcle Measurement (in touch trigger mode)	1			
one Measurement (in touch trigger mode)	Criteria - Fo	r an Inne	r Circle measurement	
onere Measurement (in touch trigger mode)	with a Radiu	us of less	than or equal to 9.999	9
rcle Measurement (in contact scanning mode)	A stiene de	6		
Defeed Defeed	Actions - de	asuring	le parameters to be	
Defined Rules	Design Mod	lel that m	eet the Criteria	
A	tions			Ado
	/leasure	• =	True	
	itting method	• =	Minimum circumscribed	-
	Automatic tool selection	• =	True	
	ampling method	• =	Contact scanning	
	ampling pattern	• =	Circle	
	oints per circle	• =	5	
	dge offset	• =	1.000	
	Rotation	• =	Clockwise	
	Circular movement	• =	False	-
	itart angle	• =	0.000000	
	nd angle	• =	0.000000	
	ampling interval	• =	By pitch	
	ican pitch	• =	0.500	
	ilter type	• =	Gaussian	
	ican points per circle	• =	100	
	ligh speed scan	• =	True	-
	can speed high	• =	10.00	
	can speed standard	• =	3.00	
	can run in angle	• =	0.000000	





Plan View

The MiCAT Plan View is multi-functional with User control over information displayed and with checkboxes for selecting the features and characteristics to be included in the Measurement Plan. Included capability allows the User to specify the desired View option for Features or Characteristics.



The features are displayed in the Plan View when the Features button is selected and when a design model is imported. In the Features pane all features of the imported design model are displayed. You can select the features to be included in the measurement by clicking the corresponding check boxes. Additional information about each feature can be displayed. such as measurement point sets and characteristics.

Ð The characteristics are displayed in the Plan View when the Characteristics button is selected and when a design model is imported. In the Characteristics pane all characteristics of the imported design model are displayed. **Characteristics** correspond to the GD&T annotations which are defined in the design model file. You can select which characteristics should be evaluated by clicking the corresponding check boxes.







Properties View

Displays the information and settings for the selected feature, characteristic (1) measurement point set (2), and measurement strategy (3) in the Plan View. Settings available in the Properties View are:

- Feature settings and information when a feature is selected
- Measurement settings when a measurement point set is selected:
 - General settings
 - Measurement tool settings
 - Measurement strategy

This shows the sampling method using **Touch Trigger** measuring using a **Measurement Strategy** of 2 circles with 5 points per circle.

This shows the sampling method using Contact Scanning using a Measurement Strategy of 2 circles with 360 points per circle.







GD&T View

When a characteristic is selected in the Plan View or in the 3D View, the GD&T View will display the feature control frame or datum label under the **Preview** group while the **Characteristic** group displays the type and name of the characteristic and its associated tolerance and datum references. The User can rework characteristics, features, and datum's by editing, deleting, or adding information.

Plan View	▼ д	×	3D View 🗙						Ŧ
💊 💁 🌮 📙	E Voint Set_3			*	۽ 🕫	ē 🌎	s 🐮 🕊	K	
🖌 🖉 💋 CIRCLE_2 🖸 🖉									
🗹 🔅 Measurement	t Point Set_3						A Ø	820.1	ABC
🔺 📝 📿 CIRCLE_3	ſ						1.		
🔽 🔅 Measurement	t Point Set_4	=							-0
☑ 🔶 Ø0.1 ⑤	A B C POSITION 🥖			-			$L \sim$		
Ø8±0.1 DIAME	TER 🖉	-		E.			7/11		ц¥
Plan View DME View							CCS		
GD&T View	- ↓	×							
Preview		*				2			· · ·
(♦ Ø0.1§	ABC	=				Ľ.			7
 Characteristic 			7						
Туре	Position -		1						
Name	POSITION								
Tolerance				→ ∧					
Tolerance value	0.1	*							
Properties View GD&T Vie	w								1

Measurement Program Button

After clicking the Measurement Program button MiCAT Planner generates a measurement program. From this point, all changes in the Plan View and Properties View are automatically synchronized with the Measurement. As with the Plan View, anything selected in the Measurement Program, the 3D View, or the Plan View displays the associated features, characteristics, measurement points, probe path, and probe changes based on the User selection.

J







Program View

The Program View displays the generated measurement program in a tree structure and provides the controls to animate the program. Animation is a 3D representation of the generated measurement program. The path and points listed in the tree structure are animated step by step in the 3D View. This provides an offline view of the measurement program running on the selected CMM



Animation Controls

The animation controls are used to animate a generated measurement program. Animation displays the tool selected for each feature and animates the measurement path and points of the generated program. This allows the

Program View	• 4 ×
■ ▲ ▶ = x2 +	G G ,
• 0:00:00	0:04:20

generated program to be verified before Translating to GEOPAK. The Program View expands to display each measurement point and the transitions between features, including any tool changes. As the animation is displayed in the 3D View, the corresponding step is highlighted in the generated program in the Program View. The animation controls are located at the top of the Program View and include:

- EVAN Stop, Play Backwards, Play Forwards and Pause (Stop and Pause only active during animation)
- • Decrease Animation Speed, Animation Speed and Increase Animation Speed

The Estimated Execution Time provides an estimate of the length of time it will take the generated measurement program to execute on a CMM. The Elapsed Execution Time can help determine where in the generated program a specific feature will be measured.

3D View

The 3D View can display the measurement path and points for a selected feature on the design model or for the entire generated program. The different display choices are available from the Hide or show measurement path and points drop-down list in the 3D View toolbar.

The path and points are color-coded to help visualize the measurement process. Dark green arrows mark the starting point for the DME tool. From the starting point, the measurement path moves to the approach point for the first feature being measured.